

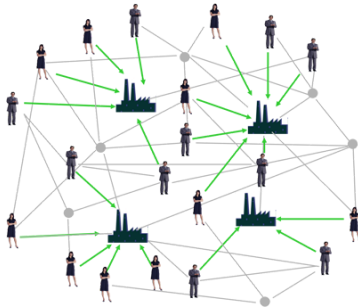
# The Facility Location Problem: Modeling and Solution Methods

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## Outline

- Introduction
- Facility Location Models
  - The Set Covering Problem (SCP)
  - The Maximal Covering Location Problem (MCLP)
- Solution Methods
- Summary



- In a basic formulation, **the Facility Location problem** consists of a set of potential facility sites  $L$  where a facility can be opened, and a set of demand points  $D$  that must be serviced. The goal is to pick a subset  $F$  of facilities to open, to **minimize the sum of distances from each demand point to its nearest facility**, plus **the sum of opening costs of the facilities**. (*Wikipedia*)
- Facility location is a critical component of *strategic planning* for a broad spectrum of public and private firms (Owen and Daskin 1998).

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## Influence Factors

- Resources, e.g. Land, Energy, Materials, Labor.
- Infrastructure, e.g. Financial Institutions, Government (stability, tax, ...), Transportation.
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## Facility Location Models

- Many analytical techniques: Factor Rating; Cost-Profit-Volume analysis; etc.
- One of **the most popular models** among facility location models is covering problem (Farahani et al 2012).
  - The Set Covering Problem (SCP)
  - The Maximal Covering Location Problem (MCLP)

**The Set Covering Problem (SCP)** tries to minimize location costs satisfying a specified level of coverage.

$$\text{minimize } \sum_{j=1, \dots, n} c_j x_j \quad (1)$$

$$\text{s.t. } \sum_{j=1, \dots, n} a_{ij} x_j \geq 1, \quad \text{for } \forall i (i = 1, \dots, m) \quad (2)$$

$$x_j \in \{0, 1\}, j = 1, \dots, n. \quad (3)$$

## Location Set Covering Problem (LSCP) Implicit and Explicit

- *LSCP-Implicit* model assumes that each demand area can be covered not only by one facility but also by two or more so that *each facility covers a percentage of demand*.
- *LSCP-Explicit* model considers the coverage provided to a demand area by a *specific* set of facilities (facility combination).

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## Capacitated SCP

- In the above models, no limitation for the capacity of a new located facility.
- Current and Storbeck (1988): capacitated version of SCP formulations.

## Multiple Optimal SCP

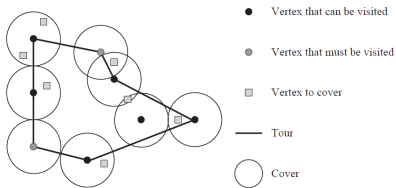
- The optimal number of the new facilities needed for total coverage.
- A secondary criterion minimizes maximum time (or distance) for all the demand points to their nearest facility.



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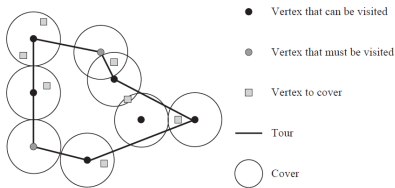
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## Covering Tour Problem



- The goal is determining a minimum length Hamiltonian cycle on a sub-set of  $V$  such that every vertex of  $W$  is within a prespecified distance from the cycle.
- Routing of a mobile medical facility.

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## Probabilistic SCP

- Consider dynamic aspect of location problems.
- In emergency facilities sometimes vehicles are not available when they are called.
- The covering constraint must be satisfied *with some prescribed probability*.

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## Stochastic SCP

- Stochasticity in demand, travel time, etc.
- Hwang (2002) applied Stochastic SCP in design a supply chain system with *random travel time* (Assume the located facilities are always available). The probability of each demand point being covered is not less than a critical level.

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## Other Variants of SCP

- **Multiple Coverage SCP**: each demand must be covered by a number of facilities (Kolen and Tamir 1990).
- Backup Coverage SCP: air ambulance and ground ambulance combination (Erdemir et al 2010).
- Fuzzy SCP
- Multi-Criteria SCP
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**The Maximal Covering Location Problem (MCLP)** maximizes the amount of demand covered within the acceptable service distance by locating a given fixed number of new facilities.

$$\text{maximize } \sum_{i=1, \dots, m} h_i z_i \quad (4)$$

$$\text{s.t. } z_i \leq \sum_{j=1, \dots, n} a_{ij} x_j, \quad \text{for } \forall i (i = 1, \dots, m) \quad (5)$$

$$\sum_{j=1, \dots, n} x_j \leq P \quad (6)$$

$$z_i, x_j \in \{0, 1\}, \quad i = 1, \dots, m, \quad j = 1, \dots, n. \quad (7)$$

## MCLP Implicit and Explicit

- Each demand area can be covered not only by one facility but also by two or more so that each facility covers a percentage of demand (**Implicit**);
- Or have to be covered by a specific set of facilities (**Explicit**).

## MCLP on the plane

- The potential sites for locating the new facilities are not on the network or discrete (and finite).

## Capacitated MCLP

- Facility capacity restriction.

## MCLP with a criticality index analysis metric

- Oztekin et al (2010): RFID network design methodology for asset tracking in healthcare.
- The objective function maximizes **the total covered criticality indices** of demand squares and also minimizes the reader collision.





## MCLP with mandatory closeness constraints

- Multiple optimal solutions.
- The objective is to seek location for  $P$  facilities to maximize population **covered within a desired time or distance**.



## Other Variants of MCLP

- Maximal Covering Tour Problem.
- Partial Coverage Problem.
- Backup Coverage Location Problem.
- ...

- Both the SCP and the MCLP are hard to solve.
- NP-Complete.

## Solution Methods for the SCP

- Exact Method.
- Approximate algorithm (Heuristics or meta-heuristics).

## Exact Method

- Branch and bound algorithm
  - **Linear programming (LP) relaxation**: Church and ReVelle (1974) and Fisher and Kedia (1990).
  - **Lagrangian relaxation**: Etcheberry (1977) and Balas and Carrera (1996).

## Approximate Method

- Heuristics
  - **Lagrangian heuristics**: Beasley (1990), Beasley and Jornsten (1992), Haddadi (1997), Caprara et al (1999), etc.
  - **Greedy heuristics**: Chavtal (1979) and Grossman and Wool (1997).
  - **Local search heuristics**: Yagiura, Kishida, and Ibaraki (2006).
  - **Others**.



## Approximate Method

- Meta-heuristics
  - **Simulated annealing**, e.g. Jacobs and Brusco (1995)
  - Genetic algorithm, e.g. Solar, Parada, and Uttutia (2002)
  - Tabu search, e.g. Kinney, Barnes and Colleti (2004)<sup>1</sup>
  - Greedy Randomized Adaptive Search Procedure (GRASP), e.g. Bautista and Pereira (2007)
  - Others

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## Solution Methods for the MCLP

- **Exact Method**: branch and bound, e.g. Downs and Camm (1996)
- **Heuristics**: Lagrangian heuristics, e.g. Galvão and ReVelle (1996)
- **Meta-heuristics**: GRASP, e.g. Resende (1998)
- **Others**







## Summary

- Facility Location Problem
- Models (SCP and MCLP)
- Solution Methods

## Major references

- Schilling D A, Jayaraman V, and Barkhi R (1993), A Review of Covering Problems in Facility Location. *Location Science*, Vol. 1, pp. 22–55.
- Farahani R Z, Asgari N, Heidari N, Hosseini M, Goh M (2012), Covering Problems in Facility Location: A Review. *Computer & Industrial Engineering*, Vol. 62, pp. 368–407.

Thank you for your attention!